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## Principles of tractor atom interferometry

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## Principles of tractor atom interferometry

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**Keywords:** atom interferometry, cold atoms in optical lattices, quantum optimal control, cold atoms in space

### Abstract

We present principles and possible design concepts for a tractor atom interferometer (TAI) based on three-dimensional confinement and transport of ultracold atoms. The confinement reduces device size and wave-packet dispersion, enables arbitrary holding times, and facilitates control to create complex trajectories that allow for optimization to enable fast splitting and recombination, to suppress detrimental nonadiabatic excitation, and to cancel unwanted sensitivity. Thus, the design allows for further advancement of compact, high-sensitivity, quantum sensing technology. In particular, we focus on the implementation of quantum-enhanced accelerometers and gyroscopes. We discuss TAI protocols for both spin-dependent and scalar trapping potentials. Using optimal control theory, we demonstrate the splitting of the wave function on a time scale two orders of magnitude shorter than a previous proposal using adiabatic dynamics, thus maximizing the time spent at full separation, where the interferometric phase is accumulated. The performance estimates for TAI give a promising perspective for atom-interferometry-based sensing, significantly exceeding the sensitivities of current state-of-the-art devices.

### 1. Introduction

Since their first demonstrations [1–4], atom interferometers [5–7] have become a powerful tool with a broad range of applications in fundamental physics, e.g., testing the equivalence principle, free fall and (non)-Newtonian forces [8–15], gravitational-wave detection [16], precision measurements of atomic constants [17–19] and applied science, e.g., inertial sensing [20–22] and geodesy [21, 23, 24]. Previous work on AI includes free-space [25–27] and point-source [28–30] AI, as well as guided-wave AI experiments [31–33] and proposals [34, 35]. Free-space and point-source AIs typically employ atomic fountains or dropped/freely expanding atom clouds. The point-source method supports efficient readout and data reduction [36], enables high bandwidth, and affords efficiency in the partial-fringe regime. Atomic fountains, typically employed in free-space AI, maximize interferometric time and thus increase sensitivity [25–27], but may require large experimental setups. Guided-wave AIs offer compactness and are often used as Sagnac rotation sensors, but are susceptible to noise in the guiding potentials. In both free-space and guided-wave AI, wave-packet dynamics along unconfined degrees of freedom can cause wave-packet dispersion and failure of the split wave packets to recombine. Coherent recombination of split atomic wave functions upon their preparation and time-evolution remains challenging in recent AI studies [37–40]. Atom interferometry is a cornerstone of space-based fundamental and applied research in the cold-atom lab (CAL [41]), where decoherence due to guide- and trap-induced forces and apparatus-size issues, otherwise encountered due to free fall, are significantly reduced. Wave-packet dispersion and atomic interactions as well as practical problems associated with efficient closure control still remain even at CAL and its successors.

Here, we describe tractor atom interferometry (TAI), a method based upon uninterrupted three-dimensional (3D) confinement and guiding throughout the AI sequence. The paper is organized as follows. In section 2 the TAI concept and its key features are explained. In section 3 we discuss an implementation with spin-dependent optical lattices of  $^{87}\text{Rb}$  on the D1 line ( $5S_{1/2} \leftrightarrow 5P_{1/2}$ ) with  $\pi/2$ -splitting and recombination pulses driven by a Raman transition. While spin-dependent lattices afford robust AI center-of-mass (COM) mode splitting [42], they require multiple lattice laser beams and have other drawbacks, explained in section 3. In section 4 we discuss a method of TAI on a scalar potential on which rapid COM mode splitting is achieved by a quantum control method. Conclusions and impacts of TAI are discussed in section 5.

## 2. Concept

TAI differs from cold-atom free-space, point-source, and guided-wave AI in that the interfering atomic wave-packet components are transported in conservative, sub-micron to mm-sized, 3D traps that are formed by tractor potentials that move on predetermined trajectories [42–44]. The traps can be implemented via optical tweezers (tractor beams) [45–48], optical lattices [49–52], RF-dressed potentials [53–57] (including ring potentials [57, 58]), optical or magnetic potentials on atom chips [59–61], etc, and any combination of these [62–64]. Uninterrupted 3D confinement in tractor traps (1) guarantees recombination, (2) allows arbitrary holding times, directional reversal, complex trajectory patterns for cancellation of sensitivities to inertial forces that are not of interest, and (3) addresses signal degradation caused by wave-function dispersion and limitations in recombination control. Ideally, the AI wave-function components are given by the 3D vibrational ground states of the tractor traps at all times during the AI sequence. As we will show in this paper, this condition may be relaxed in order to realize fast AI splitting and recombination with coherent quantum control methods. We further envision TAI initialization with low-temperature atoms from a Bose–Einstein condensate (BEC) or close to such a state. In that case, TAI is not expected to suffer excessive coherence loss due to the population of thermal states inside the individual tractor traps.

In TAI, the tractor controls (laser-beam angles, diameters, powers and phases, electric and magnetic fields) define pre-determined trajectories,  $\mathbf{x}_m(t)$ , of the tractor-potential minima in 3D configuration space. The trajectories mark the centers of the tractor traps versus time. A pair of traps, indexed by  $m = 1, 2$ , are intersecting at initial and final space–time points, denoted  $\mathbf{x}_{\text{init}}(t_{\text{init}})$  and  $\mathbf{x}_{\text{final}}(t_{\text{final}})$ , respectively. This situation, while classically forbidden due to the uniqueness of classical trajectories, can be realized in quantum mechanics by employing a pair of spin states with different, state-specific tractor traps on spin-dependent potentials that coincide at the initial and final space–time points, or by AI splitting and recombination afforded by quantum tunneling or some other type of coherent dynamics between a pair of potential wells on a spin-less (scalar) potential. In these two cases, the AI beam-splitters and re-combiners are implemented via microwave or Raman laser pulses that couple the active spin states, or by quantum manipulation on a dynamic double-well landscape, respectively.

Following the usual path integral formalism, the interferometric phase of the TAI is given by  $\Delta\Phi = \frac{S_2 - S_1}{\hbar}$ , with the actions computed as,

$$S_m = \int_{t_{\text{init}}}^{t_{\text{final}}} \mathcal{L}(\mathbf{x}_m(t), \dot{\mathbf{x}}_m(t), t) dt, \quad (1)$$

where  $\mathcal{L}$  is the Lagrangian function for a trajectory  $\mathbf{x}_m(t)$  [5]. In TAI, the latter is given by the pre-programmed center locations of the tractor traps [42], so that equation (1) can be evaluated directly, without having to perform a classical trajectory calculation first. This contrasts with AI-types that have one or more generalized classical degrees of freedom. In those cases, the classical trajectories  $\mathbf{x}_m(t)$  are not *a priori* known and must be computed *before* equation (1) can be evaluated. It is implicit to the TAI method that automatic closure of the interferometer can be guaranteed via correct tractor programming.

The dependencies of the differential interferometric phases on rotation and acceleration scale as [5]

$$\begin{aligned} \Delta\Phi_{\Omega} &= \frac{2mK\Omega \cdot \mathbf{A}}{\hbar} \\ \Delta\Phi_a &\approx \frac{mKa_zT}{\hbar}. \end{aligned} \quad (2)$$

Here,  $m$  is the atom mass,  $a$  the acceleration,  $\mathbf{A}$  the interferometric area,  $\Omega$  the frame's angular velocity measured against an inertial frame,  $K$  the number of loops in the TAI sequence,  $z$  the well separation along the acceleration vector, and  $T$  is the AI time. The expression for the acceleration phase given in equation (2)

is only approximate, because details of how the TAI wells separate and recombine play a role. The acceleration phase can be calculated accurately after the exact tractor trajectories  $\mathbf{x}_m(t)$  have been specified. A discussion of quantum-projection-limited sensitivity levels for rotation and acceleration is provided in [42]. Phase sensitivity estimates for some conditions of the presently discussed schemes are given in section 5.

While 3D confinement makes TAI robust and compact, in comparison with free-space AI, it is noted that the basic interferometric phase of split wave-packet components under acceleration or gravity is explained in textbooks, (see, e.g., section 2.6 in [65], where the observation of the gravitational phase in neutron AI [66] is reviewed in some detail). The differential motion of the traps,  $\mathbf{x}_m(t)$ , which gives rise to the phases in equation (2), must not be confused with any inertial or gravitational sags of the atomic wave-function components in their individual traps. The differential motion of the tractor traps is at the core of TAI and lends sensitivity to it according to equation (2), while the in-trap sags are ideally small. The tractor traps and their trajectories are ideally designed such that phases due to in-trap displacements are common-mode, and their effects cancel in the net interferometric phase. Also, nonadiabatic excitation of excited vibrational states in the individual tractor traps is to be minimized by using suitable tractor-trap trajectories, as discussed in detail in section 4.

TAI differs from other work on cold-atom free-space, point-source, and guided-wave implementations of AI (see section 1) in that the interfering wave-function components are confined in 3D at all times, suppressing dispersion and allowing for maximum control. Proper programming of the tractor traps ensures AI closure. The robustness of TAI closure against tractor-induced and background inertial effects is limited by the forces of constraint acting on the atoms. The forces of constraint are given by the forces that the tractor potentials exert on the trapped atoms to keep them on the pre-programmed tractor trajectories,  $\mathbf{x}_m(t)$ . The forces of constraint counter-balance the inertial forces,  $m\ddot{\mathbf{x}}_m(t)$ , in the instrument's frame of reference, as well as the inertial forces caused by the motion of the platform the instrument is mounted on. Uninterrupted 3D confinement of the atomic wave-function components in the tractor traps further eliminates uncontrolled wave-packet dispersion. Geometry and speeds of the TAI tractor trajectories are user-programmable and flexible, including multi-loop designs, trap-hold intervals, and twisted patterns. Hence, TAI can be adapted to a variety of applications.

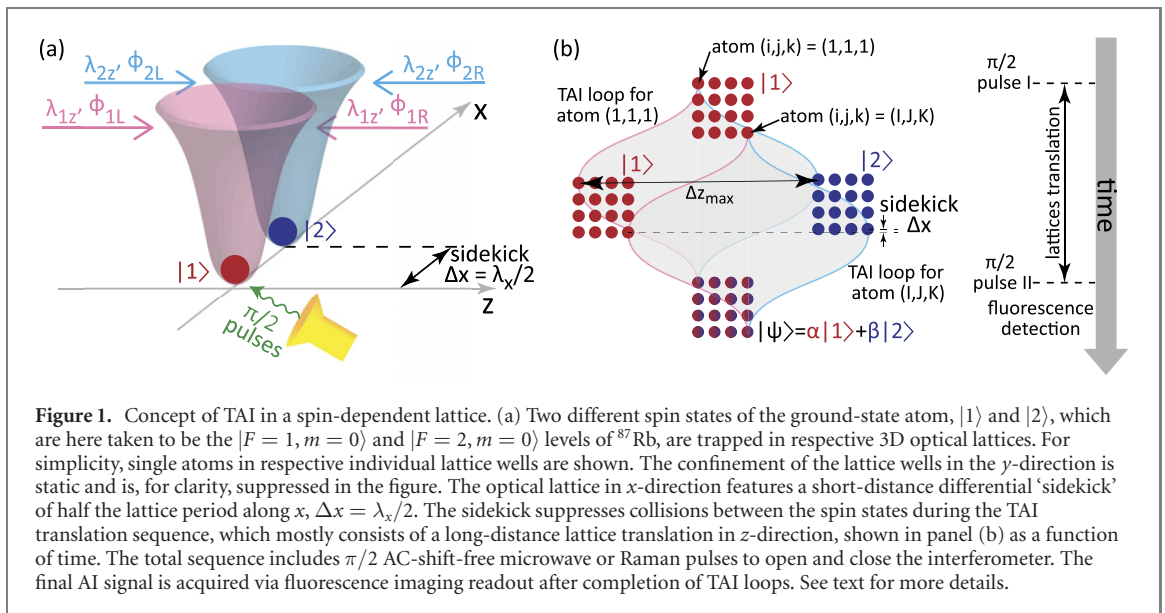
The TAI concept translates well to microgravity implementations, where the tractor-trap depth can be relaxed into the sub-Hz regime at times when the forces of constraint become very small. Trap relaxation efficiently addresses concerns with phase noise in equation (2) caused by trap-depth fluctuations. In relaxed tractor traps, the AI time,  $T$ , may extend to minutes, which translates into greatly enhanced sensitivities. Also, under such conditions the motional time scale of the atoms in the tractors becomes so slow that technical noise in the acoustic and higher-frequency bands does not couple to the vibrational dynamics of the atoms.

Here we consider primarily optical-lattice traps, which can exert forces of constraint that exceed gravity on Earth by orders of magnitude. Optical-lattice-based TAI may be implemented in scenarios that require large forces of constraint. As a result, closure in optical-lattice-based TAI can be very robust.

### 3. TAI in spin-dependent optical lattice

One implementation of TAI is based on the use of spin-dependent optical lattices. Figure 1 outlines the concept. The lattice spin states are the  $|1\rangle := |F = 1, m = 0\rangle$  (red in figure 1(a)) and  $|2\rangle := |F = 2, m = 0\rangle$  (blue) levels of  $^{87}\text{Rb}$ , which are magnetic-field-insensitive in lowest order. The states are trapped in respective 3D optical lattices with spatial periodicities  $\lambda_{m,n}$ , where the first index refers to the ket  $|m\rangle$  and the second to the spatial axes,  $n = x, y$  and  $z$ . For lattices formed by counter-propagating beam pairs the periodicities are given by half the optical wavelength ( $\lambda_{m,\text{opt}} \approx 795$  nm for the Rb D1 line). The spatial periodicities may be increased by choosing beam-pair angles  $\theta_{m,n} \leq \pi$ , for which  $\lambda_{m,n} = \lambda_{m,\text{opt}} / [2 \sin(\theta_{m,n}/2)]$ . It must be ensured that  $\lambda_{1,n} = \lambda_{2,n} =: \lambda_n$  for all  $n = x, y$  and  $z$ . The lattices for the two spin states can be translated relative to each other using independently controlled phases,  $\phi_{m,L}$  and  $\phi_{m,R}$  with  $m = 1, 2$  and L = 'left' and R = 'right' (index  $n$  is suppressed for brevity).

An implementation of TAI may proceed as follows. The lattice structures along  $y$  are static and are overlapped at all times. A differential 'sidekick' between the lattices for the  $|1\rangle$  and  $|2\rangle$  atoms displaces the respective lattice-trapped wave-function components relative to each other in the  $x$ -direction by a distance  $\Delta x = \lambda_{m,x}/2$ , i.e. half the spatial lattice period along  $x$ . In that way, the subsequent long-distance tractor motion along  $z$  will not lead to collisions between the  $|1\rangle$  and  $|2\rangle$  atoms. As shown in figure 1(b), the  $z$ -translations form a large AI area in the space-time plane, which is suitable for inertial sensing (gray areas). The lattice has  $I \times J \times K$  sites, with  $I, J$ , and  $K$  denoting the number of sites in the  $x, y$  and  $z$ -directions, and integer indices  $(i, j, k)$  labeling individual sites. Figure 1(b) shows the TAI trajectories for



the corner sites  $(1, 1, 1)$  and  $(I, J, K)$ . The AI sequence involves  $\pi/2$  AC-shift-free microwave or Raman pulses to open and close the interferometer. An AI signal can be acquired via imaging of spin-dependent fluorescence after completion of the TAI loops.

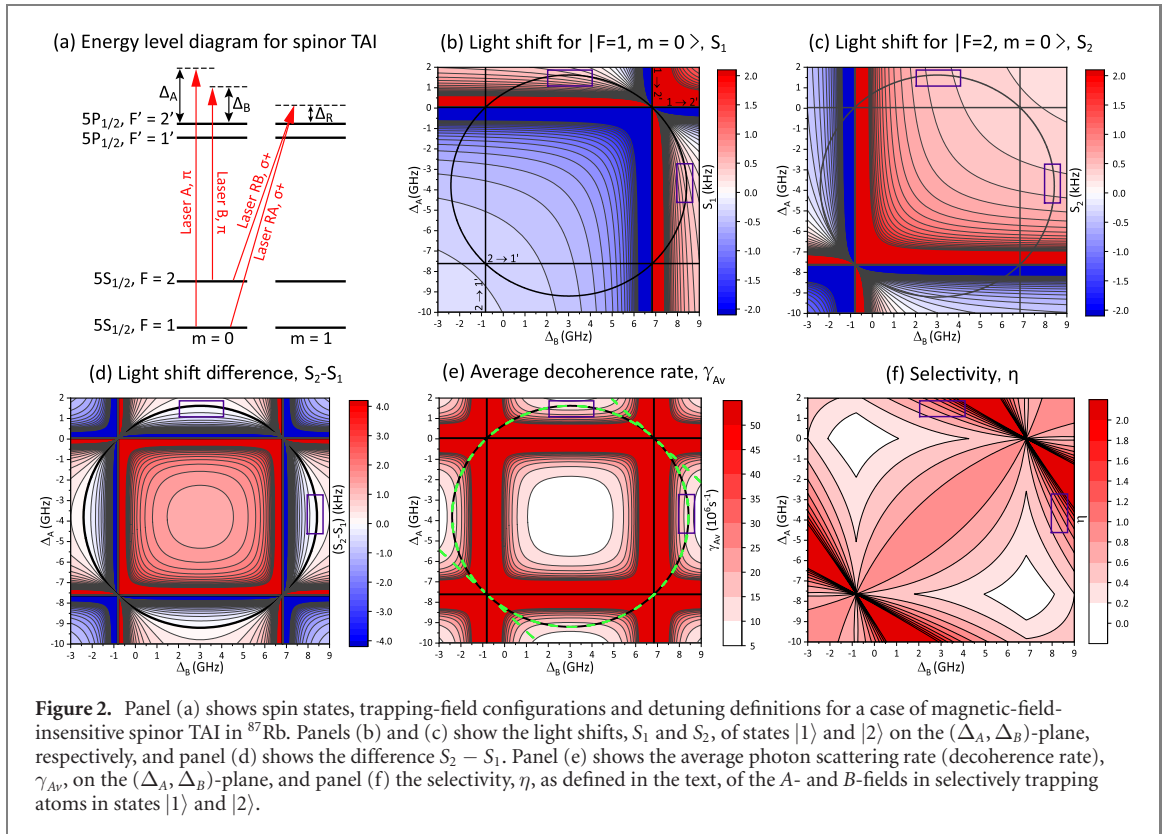
We note that the actual laser-beam frequencies for trapping along  $x$ ,  $y$  and  $z$  have to differ by an amount significantly larger than the vibrational frequencies of the atoms in the lattice traps to exclude any effects of optical interference beats on the COM (vibrational) wave functions of the trapped atoms. It is expected that this condition will be satisfied in most practical implementations of optical-lattice-based TAI. Further, since each lattice site must be split and recombined with itself, accurate control of the lattice phases,  $\phi_{m,L}$  and  $\phi_{m,R}$ , is critical for successful implementation of lattice-based TAI. The phase controls may be implemented using optical phase shifters that apply sequences of adiabatic  $2\pi$ -sweeps and (near-instantaneous)  $2\pi$ -steps, with uncertainties at a level of a small fraction of  $2\pi$ . Alternatively, one may apply optical frequency sweeps; in that case, the integral of angular-frequency shift over time must maintain an accuracy and a precision of a small fraction of  $2\pi$ . These and other technical details will be addressed in future work.

We first discuss the case of spin-dependent lattices formed with a pair of near-resonant laser fields near the D1 line of Rb (wavelength  $\lambda_{m,\text{opt}} \approx 795$  nm for  $m = 1$  and  $2$ ). The two fields are labeled  $A$  and  $B$  (see figure 2(a)). Each one of the indicated magnetic-field-insensitive spin states,  $|1\rangle$  and  $|2\rangle$ , exhibits two light shifts from fields  $A$  and  $B$  that we label  $S_{m,A}$  and  $S_{m,B}$ , with  $m = 1, 2$ . The net shift for each level then is  $S_m = S_{m,A} + S_{m,B}$ . All shifts depend on atom-field detuning. For specificity, we measure the frequency offset of the  $A$ -field relative to the  $F = 1$  to  $F' = 2$  hyperfine transition of the  $^{87}\text{Rb}$  D1 line, and that of the  $B$ -field relative to the  $F = 2$  to  $F' = 2$  transition (see figure 2(a)). The respective frequency detunings are denoted  $\Delta_A$  for the  $A$ - and  $\Delta_B$  for the  $B$ -field. For a sample case of equal electric-field amplitudes of  $E_A = E_B = 100$  V m $^{-1}$ , in figures 2(b) and (c) we show the level shifts for the spin states  $|1\rangle$  and  $|2\rangle$ , respectively, and in figure 2(d) the difference,  $S_2 - S_1$ .

In addition to reducing phase fluctuations caused by differential trap-beam intensity noise, it is imperative to reduce coherence loss due to photon scattering of trap-beam light. Coherently-split wave-function components as sketched in figure 1 are susceptible to this type of coherence loss. As a quantitative figure, we use the photon scattering rate of a coherently split atom averaged over both internal spin states. Denoting the scattering rate of the atom in pure spin state  $|m\rangle$  due to fields  $A$  and  $B$  as  $\gamma_{m,A}$  and  $\gamma_{m,B}$ , with  $m = 1, 2$ , respectively, the scattering rate in spin state  $|m\rangle$  is  $\gamma_m = \gamma_{m,A} + \gamma_{m,B}$ . Assuming that the atomic wave packets are split evenly between the spin states, the average scattering rate is  $\gamma_{Av} = (\gamma_1 + \gamma_2)/2$ , which is shown in figure 2(e). Unsurprisingly, it is seen in figure 2(e) that the overall scattering is minimized if both detunings  $\Delta_A$  and  $\Delta_B$  are about equally far away from the nearest hyperfine resonances. Since the light shifts, their difference, and the photon scattering rates all scale linearly in field intensity, the results in figure 2 easily scale to configurations with different (but equal) fields,  $E_A = E_B$ . Slight modification of the calculation also allows one to consider cases with  $E_A \neq E_B$ .

Inspection of figure 2 shows that detuning combinations in the  $(\Delta_A, \Delta_B)$ -plane that minimize photon scattering under the condition  $S_1 = S_2 \approx 400$  Hz have  $\gamma_{Av} \approx 12$  Hz, so that  $S_m/\gamma_{Av} \approx 40$ . It becomes obvious that TAI with spin-dependent lattices will require blue-shifted configurations, in which the light-shift traps localize the atoms at locations of minimal field intensity, hence minimizing the actual

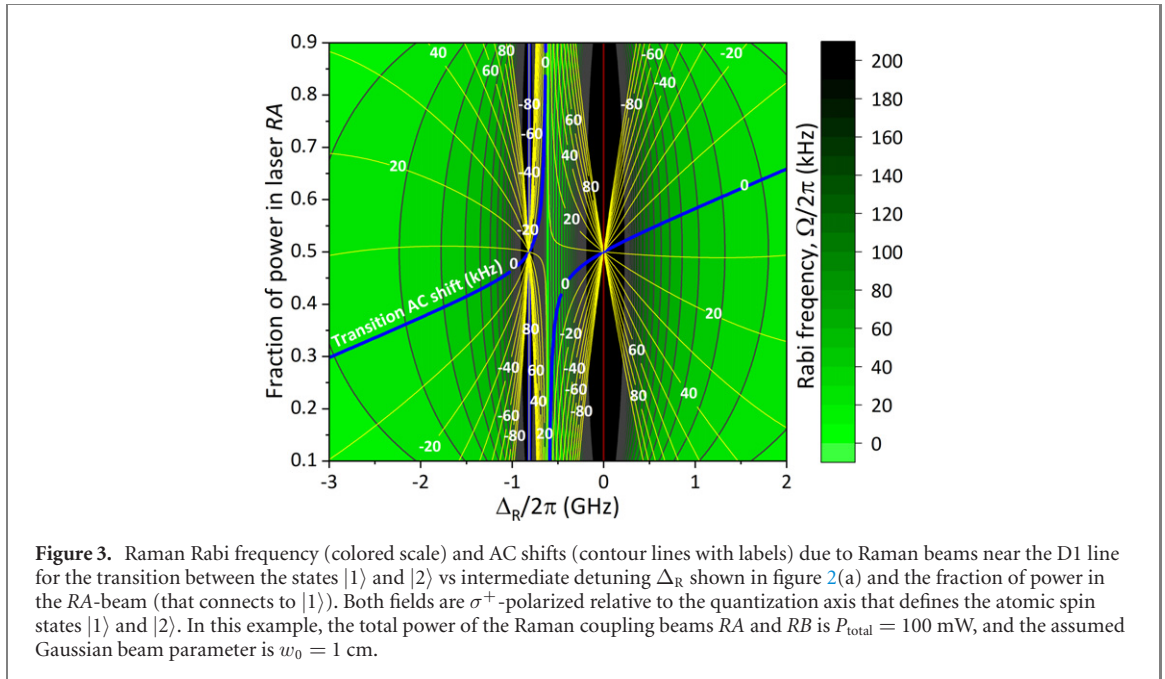




photon scattering rate (decoherence rate). This corresponds with regions within the blue rectangles in figure 2. At the field minima in low-field-seeking lattice traps one may then expect effective coherence loss rates on the order of  $\sim 1/500$  of the trap depth. While this may suffice for demonstrations, high-precision AI with long AI times  $T$  will require schemes with a lower coherence loss rate during times at which the wave-function components are held at a large mutual separation. This may be achievable by combinations of laser-intensity sweeps and laser-frequency sweeps farther away from resonance. The sweeps enable a reduction of the decoherence rate at times when the wave-function components are spatially separated. Effectiveness of such methods will require that the wave-function components are spatially separated during most of the AI time  $T$  (which is, typically, the case).

Another figure of merit that applies, in particular during the splitting phase of TAI, is the degree to which the optical potentials are spin-dependent. For the survey presented here, we compute the spin-selectivity figure  $\eta_m = (\pm S_{m,A} \mp S_{m,B}) / (S_{m,A} + S_{m,B})$ , where the upper signs apply to state  $|1\rangle$  and the lower ones to  $|2\rangle$ . In an ideal scenario of perfect spin selectivity, field  $A$  would only trap state  $|1\rangle$  and not induce AC shifts in state  $|2\rangle$ , and similarly field  $B$  would only trap state  $|2\rangle$  and not induce AC shifts in state  $|1\rangle$ . In that case, it would be  $\eta_1 = \eta_2 = 1$ . For a comprehensive reading, in figure 2(f) we only show  $\eta = (|\eta_1 - 1| + |\eta_2 - 1|) / 2$ . Ideal selectivity will then require  $\eta = 0$ , and the more  $\eta$  exceeds the value of 1 the more marginal the spin selectivity will become. The results for  $\eta$ , presented in figure 2(f), show that ideal spin selectivity only occurs in regions on the  $(\Delta_A, \Delta_B)$ -plane where the decoherence rate is large. A compromise between reasonably low decoherence rates and high spin selectivity of the traps occurs near the left margin of the upper blue rectangle and near the lower margin of the lower blue rectangle in figure 2.

We next consider the  $\pi/2$  beam-splitting in spinor TAI for opening and closing the interferometer. For the case considered here, the transition  $|1\rangle \rightarrow |2\rangle$  can be coherently driven with an RF field at the ground-state hyperfine splitting frequency of 6.8 GHz or via an optical Raman transition. Since the pulse time must be much smaller than the AI time  $T$ , we envision coupling Rabi frequency,  $\Omega$ , in the range of 50 kHz. These will enable  $\pi/2$ -pulses with durations  $\lesssim 0.01$  ms even for cases of short TAI sequences with  $T \sim 1$  ms, as will be required in initial testing of TAI. For specificity, here we consider an optical Raman coupling with field polarizations as shown in figure 2(a). The Raman transition has two variables, the Raman detuning,  $\Delta_R$ , and the power splitting ratio between the two fields driving the transition. We seek a configuration that results in a decent  $\Omega$ , while minimizing the light shift due to the Raman-transition fields. In figure 3 we show  $\Omega$  vs  $\Delta_R$  and the fraction of power in the  $RA$ -beam (which connects to the  $|1\rangle$ -state). The overlay shows the AC shift induced by the Raman beams. For the anticipated pulse durations of  $\sim 0.01$  ms,  $\Omega$  near 50 kHz and an AC shift of  $\lesssim 10$  kHz would be desirable. Figure 3 shows that such conditions



can be attained with  $\Delta_R \approx 1.5$  GHz and about  $2/3$  of the power in the RA-beam, for the net laser power and beam size as specified in the caption.

Figures 2 and 3 can be summarized as follows. It is possible to generate spin-dependent lattices for pairs of magnetic-field-insensitive hyperfine ground states of alkali atoms using two lattice laser fields with different frequencies. The lattices can be ‘magic’, in a sense that both spin states experience the same trapping potentials for phases  $\phi_{m,L}$  and  $\phi_{m,R}$  in figure 1 at which the spin-dependent potentials are overlapped. The magic condition simplifies efficient  $\pi/2$  AI splitting between the vibrational ground levels of the spin states  $|1\rangle$  and  $|2\rangle$  in their respective lattices, and it reduces AI phase noise in  $\Phi$  (see equation (2)) caused by laser intensity fluctuations. Decoherence rates due to photon scattering limit the AI time,  $T$ , to values on the order of 500 times the inverse of the trap depth (in Hz). Parameters that yield sufficient spin selectivity of the traps as well as AC-shift-free  $\pi/2$  Raman pulses for opening and closing the interferometer exist. For spinor-TAI with long interferometer times  $T$ , required to reach high sensitivities for inertial fields, it will be necessary to use combinations of laser-intensity sweeps and laser-frequency sweeps to intermittently reduce decoherence rates due to photon scattering at times when the wave-function components are spatially separated, in a manner that 3D trapping at all times is maintained. In this scenario, the lattice tractor traps become spin-independent at the times when the spin components are separated, because the trap laser fields will be temporarily swept far-off-resonance to reduce the photon scattering.

While we believe that the spinor TAI method can be realized in the laboratory, it also is prudent to consider scalar TAI [42] as an alternative method. In scalar TAI, the laser fields can be held far-off-resonance at all times, allowing one to reduce decoherence caused by photon scattering to practically zero. In scalar TAI, the trapping laser will be far-off-resonant, allowing the use of high-power, highly efficient lasers (for instance, YAG lasers or frequency-doubled telecom lasers). There will be only a single trapping potential, on which single wells are split into double wells. These follow different tractor trajectories and are recombined back into single wells at AI closing. The challenge in that scheme is to provide fast splitting without exciting the split wave packets into higher vibrational states of the atoms in the tractor traps [42]. In the following section we will present a method of scalar TAI that employs rapid beam splitters that are based on quantum-state engineering methods.

#### 4. Scalar TAI with quantum-state-engineering-enabled beam splitters

In the spin-less (or scalar) case, the goal is to split the wave function into a superposition of each tractor trap ground state as quickly as possible. This maximizes the available time for accumulating a differential phase. Mathematically, the goal is to find the tractor functions  $\mathbf{x}_m(t)$  that minimize the functional

$$J[\mathbf{x}_m(t)] = |\langle \Psi_{\text{tgt}} | \Psi(T_s) \rangle|^2, \quad (3)$$

where  $|\Psi_{\text{tgt}}\rangle = (|\Psi_{\text{L}}\rangle + |\Psi_{\text{R}}\rangle)/\sqrt{2}$  is the target state,  $|\Psi_{\text{L,R}}\rangle$  are the ground states of each trapping potential when separated at a distance  $\Delta z$ , and  $|\Psi(T_s)\rangle$  is the system state after allowing a time  $T_s$  for splitting. The functional corresponds to the fidelity at the end of the splitting. To preserve the symmetry between the arms, we assume  $\mathbf{x}_1(t) = -\mathbf{x}_2(t) = \mathbf{x}(t)$ . In this way, we only need to find a single tractor function. Furthermore, we assume that the trapping potential only allows movement in the  $z$  direction so that the dynamics can be described as  $\mathbf{x}(t) = z(t)\hat{z}$ , where  $\hat{z}$  is the unit vector in the  $z$  direction. Consequently, the equation of motion is

$$i\hbar\frac{\partial}{\partial t}\Psi(z,t) = H(z,t)\Psi(z,t), \quad \text{with} \quad (4)$$

$$H(z,t) = -\frac{\hbar^2}{2m}\frac{\partial^2}{\partial z^2} + V(z-z(t)) + V(z+z(t)),$$

where  $V(z) = -V_0 \exp[-2 \log(2)z^2/d^2]$  is the trapping potential. For a specific example, we use the parameters  $V_0 = 0.5$  MHz for the potential depth,  $d = 23.5 \mu\text{m}$  for the full width at half maximum, and the mass of the  $^{87}\text{Rb}$  atom for  $m$ . These parameters equal those used in reference [42].

In reference [42], the tractor function  $z(t)$  was tuned adiabatically, so that  $\Psi(z,t)$  is the ground state of the shifted  $V(z(t))$  at all times. The time scale for achieving an adiabatic separation is on the order of seconds, that is, comparable to the accumulation time when the wave packets remain at maximum separation. When  $z(t)$  changes faster than adiabatically in order to minimize  $T_s$  and maximize the accumulation time, the movement can produce unwanted excitations and even cause the particles to escape the trap. We will demonstrate that coherent quantum control can refocus the dynamics to remove these nonadiabatic effects, thus achieving fast splitting.

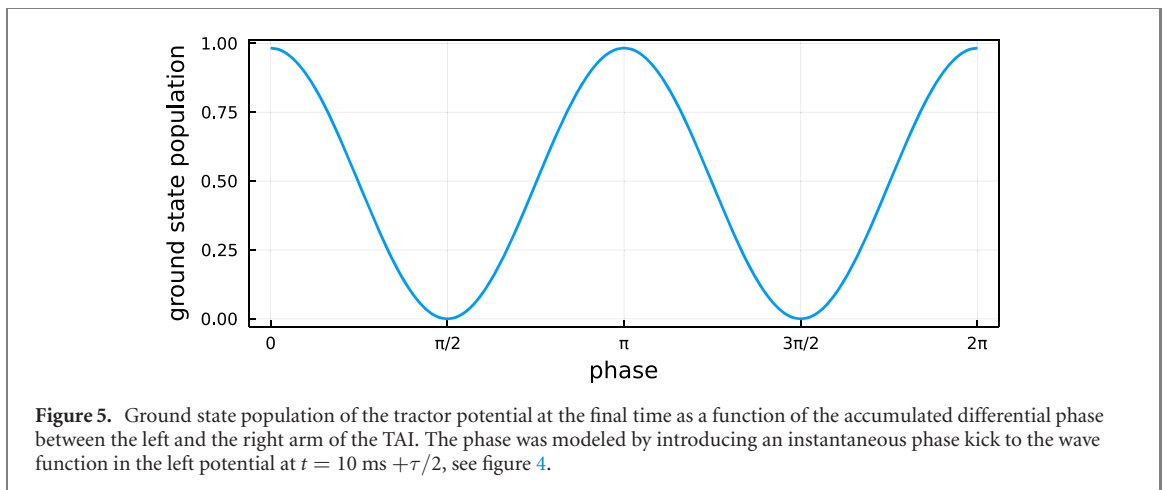
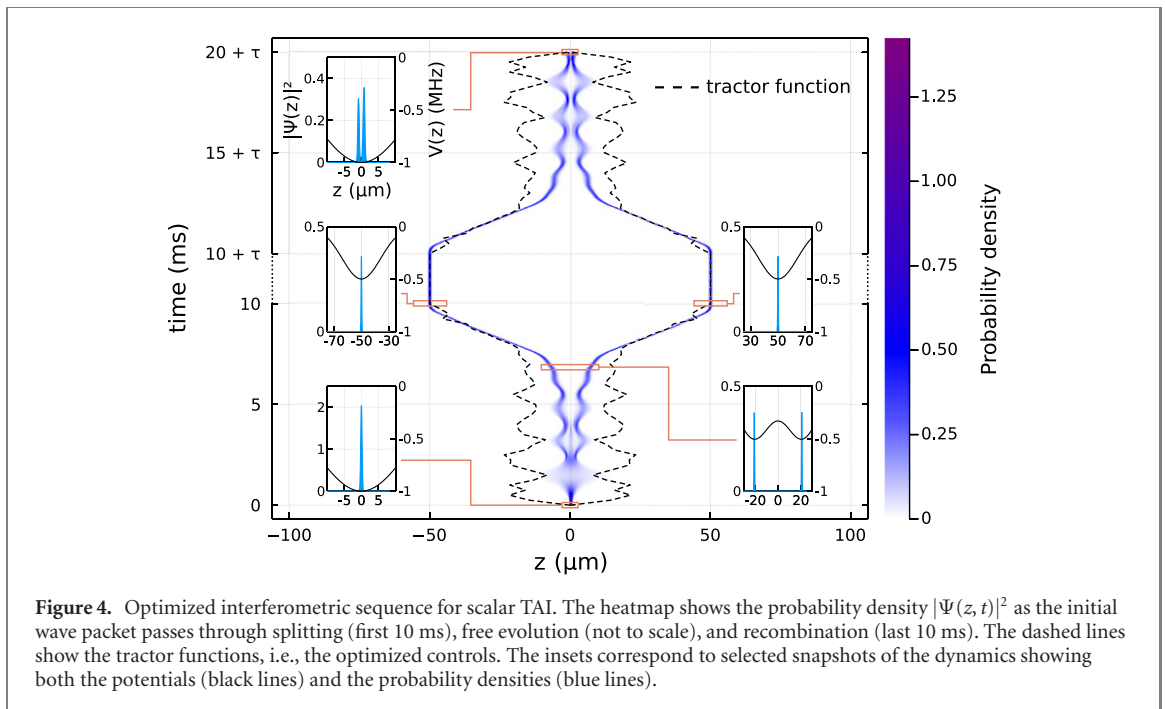
We will use the following approach for coherent quantum control. Given a value of  $T_s$ , we set the  $x$  and  $y$  components of the tractor function to zero and specify the  $z$  component as a piecewise linear function with  $n$  equally spaced segments. Therefore, the tractor function is fully described by  $n - 1$  parameters, i.e., the values of the tractor function  $x_j$  at the carrier points  $t_j$ . The values at  $t = 0$  and  $t = T_s$  are fixed at 0 and  $\Delta z$ , respectively. The piecewise linear ansatz reduces the dimensionality of the parameter space sufficiently to find a ‘guess’ tractor function with non-zero fidelity by testing random seeds.

Once we find an appropriate guess solution, we can calculate the gradient  $\partial J/\partial z_j$  using central finite differences and use it to feed a quasi-Newton gradient-based optimizer such as L-BFGS-B [67]. Each evaluation of  $J$  runs in parallel using a split-operator scheme [68] to propagate the wave function according to equation (4). If further refinement is required, we can double the number  $n$  of segments, matching the lower-dimensional solution, and repeat the optimization. Another advantage of this approach is that it decouples the number of control parameters from the number of time steps. This is useful when the time scale of the dynamics inside the trap is much faster than the splitting timescale.

Figure 4 illustrates the entire scalar TAI scheme using the coherent quantum control solution, including both splitting and recombination. The heatmap represents the probability density. The dashed lines show the tractor function, i.e., the minima of the trapping potentials. The insets show the probability density and the overall potential (the sum of both trapping potentials) at different time instances. When calculating the tractor function, we start with 10 segments, corresponding to 11 carrier points distributed over a splitting time of  $T_s = 10$  ms, and obtain a fidelity of 0.826. We then increase the number of segments to 80 (81 carrier points distributed over the same  $T_s$ ), to obtain a fidelity of 0.991. This splitting time represents an improvement over the original spin-less TAI result [42] by two orders of magnitude. As shown in figure 4, the tractor function does not simply separate both trapping potentials to split the wave function but oscillates to refocus it and avoid unwanted excitations. After that, the wave function starts to travel with the minima of the trapping potential to the maximum separation (see the bottom right inset). Before reaching maximum separation, the tractor function suddenly reduces the separation to decelerate the wave packets, so they remain in the ground state for a time  $\tau$  to accumulate the interferometric phase (see middle insets). Note that the accumulation time is typically several orders of magnitude longer than the splitting time. Finally, the recombination repeats the splitting process, but running backward. In the end, we obtain a state that is a linear combination of the ground state and the excited state, with the relative population depending on the accumulated phase (see top inset).

To demonstrate the performance of the complete scalar TAI interferometric scheme, we propagate the atomic wave packet according to equation (4). After splitting ( $T_s = 10$  ms in figure 4), we add an instantaneous phase kick to the wave-function component in the left tractor potential and then calculate the ground state population after recombination ( $t = 20$  ms  $+\tau$  in figure 4). In figure 5, we plot the population of the ground state as a function of the interferometric phase. We obtain a sinusoidal function as expected for the device. A loss of contrast on the order of 2% due to residual population in other levels is observed. However, the sensitivity gain will be more significant than the contrast loss as the speed-up allows to





maintain the atoms separated at the maximum distance for a longer time. Moreover, the contrast loss can be further reduced by applying, for example, a penalty on the population of unwanted states or more advanced optimal control techniques [69, 70].

## 5. Discussion and conclusions

In this work, we describe a concept and some key features of TAI based on 3D-confined guiding of cold atoms through controllable predetermined channels. Several implementation schemes of TAI have been discussed to provide a way to estimate AI performance. We have assumed that the atoms are initialized in the vibrational ground state of the individual optical-lattice wells. This could be accomplished, for instance, by adiabatic ramp-up of the lattice within a moderately de-compressed BEC. In this way, a Mott-insulator state with an occupation number of one in each well, the most ideal condition, could be prepared prior to the TAI splitting [71]. Detailed studies of atomic-temperature and mean-field effects will be the subject of future investigations. Microgravity will afford the use of extremely shallow and large super-relaxed TAI wells with a virtual absence of tunneling. Such features promise high levels of performance to address topics in the areas of fundamental physics and low- $g$  navigation. ‘Magic’ optical-tractor wells with depths in the sub-Hz regime, prepared with intensity-leveled trapping beams, are expected to afford splitting times exceeding several minutes, as well as macroscopic distances between coherently split wave-function components. These capabilities, combined with dispersion-free, 3D uninterrupted wave-function

confinement shared among all TAI implementations, and with quantum correlated (entangled or spin-squeezed) atomic ensembles [72] to move toward the Heisenberg quantum-sensing limit, form prerequisites for future transformative progress in high-precision AI.

TAI offers compactness and can be used as various inertial sensors to measure acceleration, gravity, and rotation. For a performance estimate of acceleration sensitivity, we use  $T = 100$  s and  $z = 0.1$  m and a phase resolution of  $2\pi/100$  to find  $\delta a = 5 \times 10^{-13}$  g. The spinor case also allows for introducing spin squeezing, which can further improve sensitivity by an extra order of magnitude, reaching  $\delta a = 5 \times 10^{-14}$  g. These figures surpass state-of-the-art sensitivities ( $10^{-9}$  g [14]) due to the long hold time afforded by TAI and the squeezing. For angular frequency sensitivity, we assume an area of  $A = 0.01$  m<sup>2</sup>, a phase resolution of  $2\pi/100$  and  $K = 10$  loops (which can be traversed within 100 s) to find a resolution of  $\delta\Omega = 2 \times 10^{-10}$  rad s<sup>-1</sup>, which improves to  $\delta\Omega = 2 \times 10^{-11}$  rad s<sup>-1</sup> employing spin-squeezed atomic states. These estimates also compare favorably to the state of the art.

Regarding coherent quantum control, we have demonstrated its ability to speed up the splitting and recombination dynamics for the spin-less case by two orders of magnitude. Consequently, we foresee at least a similar speed-up for the spinor and Sagnac interferometers, where nonadiabaticity also plays a role. Moreover, one could incorporate more elaborate numeric approaches and functionals to maximize fidelity and increase robustness due to imperfections in the controls. In particular, one could replace the piece-wise linear function with more flexible parametrizations or arbitrary control functions. These can then be designed via traditional optimal control methods [73] or more novel machine learning methods such as reinforcement learning [74].

The precision of AIs enables the search for dark matter [75, 76], the detection of gravitational waves [16, 76–79], and inertial navigation [21]. There is considerable untapped potential in further advances within these devices. Improvements in atomic clocks would significantly enhance the long-term stability of navigation and timekeeping in situations where communication and re-synchronization are limited. AI-based gravity gradiometers can reach sensitivities of several orders of magnitude beyond conventional gravity sensors, allowing them to detect dense materials in shipping containers or underground structures. We believe that AI-based sensors for navigation, fundamental physics research, and remote probing of celestial bodies via AI-based geodesy will play a crucial role in future NASA missions.

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## Data availability statement

The data that support the findings of this study are available upon reasonable request from the authors.

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